# Regularized supermembrane theory and static configurations of M-Theory 

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#### Abstract

We suggest that the static configurations of M-theory may be described by the matrix regularization of the supermembrane theory in static regime. We compute the long-range interaction between a M2-brane and an anti-M2-brane in agreement with the 11-dimensional supergravity result.


## 1 Introduction

The proposed M (atrix) model [1] as a non-perturbative formulation of M-theory [2] has provided a new and effective framework for studying dualities and connections between different string theories [3-7]. This model is the dimensional reduction of $9+1 U(N)$ SYM theory to $0+1$ dimension [8] in the large- $N$ limit, which latter was introduced and studied as the dynamics of $N$ D0-branes [9, 10].

In the initial developments of the supermembrane theory $[11,12]$ in an 11-dimensional supergravity background, it was observed that the existence of $\kappa$-symmetry imposes restrictions on the background fields which reduce to the 11-dimensional supergravity field equations. Since M-theory has the 11-dimensional supergravity as its low energy limit, the above observation suggests that every definition of M-theory should be closely connected to supermembrane theory. Thus, M-theory in an infinite momentum frame and supermembrane action in light-cone gauge, written in a matrix form, are related [1].

On the other hand, in the formulation of the M (atrix) model for M-theory the notion of a substructure has played a central role. Therefore it is plausible to expect that the same substructure, in the form of a matrix formulation, should play a role in the framework describing the static configurations of the M-theory.

As there is no definition for covariant M-theory, it is tempting to study it in various gauges: light-cone, static, etc. The above mentioned relations between supermembrane theory and M-theory in light-cone gauge motivates us to search for a similar relation in static gauge. Our

[^0]starting point is the action of supermembranes in 11 dimensions. By restricting the action to the static part of its phase space, we obtain an action which, after its $\kappa$ symmetry is fixed, be written in matrix form.

The resulting matrix action is invariant under $S O(9)$ rotations of target space. Also, the action has a gauge symmetry which corresponds to the world volume areapreserving symmetry. Despite the existence of the gauge symmetry, the interpretation of the model as a dimensional reduction of SYM theory seems impossible.

We introduce solutions for the action, which, as is expected from M-theory, have vanishing quantum corrections. We also calculate the long- range interaction of parallel M2-brane and anti-M2-brane solutions of the matrix model. The result is $W(r) \sim 1 / r^{6}$, which agrees with the uncompactified 11-dimensional supergravity, in direct in contrast to the light-cone M (atrix) theory result in compactified limit $W(r) \sim 1 / r^{5}$.

Conventions and some calculations are gathered in appendices.

## 2 Static supermembrane action as a matrix model

We use the following notations everywhere:

$$
\begin{gathered}
a, b=0,1,2 ; \mu, \nu=0,1, \ldots, 9,10 \\
I, J, K=1,2, \ldots, 9,10 ; \quad \text { and } i, j, k=1,2, \ldots, 9 .
\end{gathered}
$$

The supermembrane action in 11 dimensions is $[13,11]$

$$
\begin{align*}
S & =\frac{-1}{2} \int \mathrm{~d}^{3} \eta(2 \sqrt{-g} \\
& \left.+\epsilon^{a b c} \bar{\theta} \Gamma_{\mu \nu} \partial_{a} \theta \times\left(\Pi_{b}^{\mu} \partial_{\mathrm{c}} X^{\nu}+\frac{1}{3} \bar{\theta} \Gamma^{\mu} \partial_{b} \theta \bar{\theta} \Gamma^{\nu} \partial_{\mathrm{c}} \theta\right)\right) \tag{1}
\end{align*}
$$

where $\Pi$ and $g$ are

$$
\begin{equation*}
\Pi_{a}^{\mu}=\partial_{a} X^{\mu}+\bar{\theta} \Gamma^{\mu} \partial_{a} \theta, \quad g_{a b}=\Pi_{a} \cdot \Pi_{b} \tag{2}
\end{equation*}
$$

and $\theta$ is an 11-dimensional Majorana spinor.
The action (1) is invariant under the global supersymmetry (SUSY) transformation

$$
\begin{equation*}
\delta X^{\mu}=-\bar{\epsilon} \Gamma^{\mu} \theta, \quad \delta \theta=\epsilon, \tag{3}
\end{equation*}
$$

and also under the local fermionic symmetry, $\kappa$-symmetry

$$
\begin{equation*}
\delta X^{\mu}=\bar{\kappa}(1-\Gamma) \Gamma^{\mu} \theta, \quad \delta \theta=(1-\Gamma) \kappa \tag{4}
\end{equation*}
$$

where

$$
\Gamma=\frac{\epsilon^{a b c}}{6 \sqrt{-g}} \Pi_{a}^{\mu} \Pi_{b}^{\nu} \Pi_{c}^{\rho} \Gamma_{\mu \nu \rho}, \quad \Gamma^{2}=1
$$

We decompose the coordinates as $\eta_{a}=\left(\tau, \sigma_{r}\right), r=1,2$.
We go to the static regime defined by

$$
\begin{equation*}
X^{0} \equiv \tau, \quad \dot{X}^{I} \equiv \dot{\theta} \equiv 0 \tag{5}
\end{equation*}
$$

then the components of $g$ are found to be

$$
\begin{align*}
g_{00} & =-1, \quad-f_{r} \equiv g_{0 r}=-\bar{\theta} \Gamma^{0} \partial_{r} \theta \\
g_{r s} & =\bar{g}_{r s}-f_{r} f_{s}, \quad \text { and } \quad \bar{g}_{r s} \equiv \Pi_{r I} \Pi_{s I} \tag{6}
\end{align*}
$$

and it can easily be shown that,

$$
\begin{align*}
& g=-\bar{g} \\
& \bar{g}=\operatorname{det} \bar{g}_{r s}=\frac{1}{2} \epsilon^{r s} \epsilon^{r^{\prime} s^{\prime}} \bar{g}_{r r^{\prime}} \bar{g}_{s s^{\prime}}=\frac{1}{2}\left(\epsilon^{r s} \Pi_{r}^{I} \Pi_{s}^{J}\right)^{2} . \tag{7}
\end{align*}
$$

Putting all the above relations into (1), we obtain

$$
\begin{align*}
S & =\frac{1}{2} \int \mathrm{~d} \tau \mathrm{~d}^{2} \sigma\left(-e^{-1}-e \bar{g}\right. \\
& \left.-2 \epsilon^{r s} \bar{\theta} \Gamma_{0 I} \partial_{r} \theta \partial_{s} X^{I}-\epsilon^{r s} \bar{\theta} \Gamma_{0 I} \partial_{r} \theta \bar{\theta} \Gamma^{I} \partial_{s} \theta\right) \tag{8}
\end{align*}
$$

where $e$ appears as an auxiliary field for linearizing the action; its equation of motion gives

$$
\begin{equation*}
e^{2} \bar{g}=1 \tag{9}
\end{equation*}
$$

which can be used for eliminating $e$. Due to (9), configurations with $\bar{g}=0$ are unacceptable.

The action (1) has a local fermionic symmetry, called $\kappa$-symmetry, which allows one to gauge away half of the fermionic degrees of freedom of $\theta . \theta$ is a 32 -component 11-dimensional Majorana spinor and is real in a real representation of $\Gamma$ matrices, which we use (see Appendix 1). We fix the $\kappa$-symmetry by the light-cone gauge ${ }^{1}$ : (i.e. $\left.\left(\Gamma^{0}+\Gamma^{10}\right) \theta=\Gamma^{+} \theta=0\right)$

$$
\begin{equation*}
\theta=\frac{1}{2}\binom{\lambda}{\lambda}, \quad \lambda=\lambda^{*} . \tag{10}
\end{equation*}
$$

[^1]Then it can be shown that

$$
\begin{align*}
\bar{\theta} \Gamma_{i} \partial \theta & =0, \quad \bar{\theta} \Gamma_{10} \partial \theta=-\frac{1}{2} \lambda^{\mathrm{T}} \partial \lambda, \\
\bar{\theta} \Gamma_{0 i} \partial \theta & =-\frac{1}{2} \lambda^{\mathrm{T}} \gamma_{i} \partial \lambda, \quad \bar{\theta} \Gamma_{0,10} \partial \theta=0 . \tag{11}
\end{align*}
$$

After integration over $\tau$ ( which gives $\mathcal{T}$ ), the action (8) takes the form

$$
\begin{align*}
S & =-\frac{1}{2} \mathcal{T} \int \mathrm{~d}^{2} \sigma e^{-1}\left(\frac{1}{2}\left\{X^{i}, X^{j}\right\}^{2}\right. \\
& +\left(\left\{X^{i}, X^{10}\right\}-\frac{1}{2} \lambda^{\mathrm{T}}\left\{X^{i}, \lambda\right\}\right)^{2} \\
& \left.+\lambda^{\mathrm{T}} \gamma_{i}\left\{X^{i}, \lambda\right\}+1\right), \tag{12}
\end{align*}
$$

where

$$
\begin{align*}
\{a, b\} & =e\left(\partial_{\sigma_{1}} a \partial_{\sigma_{2}} b-\partial_{\sigma_{2}} a \partial_{\sigma_{1}} b\right) \\
& =e \epsilon^{r s} \partial_{r} a \partial_{s} b, \tag{13}
\end{align*}
$$

which satisfies the Jacobi identity.
We can now formulate our matrix model. By the usual substitutions $[13,1,14]^{2}$

$$
\begin{equation*}
\{a, b\} \Rightarrow-i[a, b], \quad \int e^{-1} \mathrm{~d}^{2} \sigma \Rightarrow \operatorname{Tr} \tag{14}
\end{equation*}
$$

with the following consequences:

$$
\begin{align*}
& \int e^{-1} \mathrm{~d}^{2} \sigma(\{a, b\} c)=\int e^{-1} \mathrm{~d}^{2} \sigma(a\{b, c\}) \Rightarrow \\
& \operatorname{Tr}([a, b] c)=\operatorname{Tr}(a[b, c]), \\
& \int e^{-1} \mathrm{~d}^{2} \sigma\{a, b\}=0 \Rightarrow \operatorname{Tr}[a, b]=0, \tag{15}
\end{align*}
$$

one then finds

$$
\begin{align*}
S & =-\frac{1}{2} \alpha \mathcal{T} \operatorname{Tr}\left(\frac{1}{2}\left[X^{i}, X^{j}\right]^{2}\right. \\
& +\left(\left[X^{i}, X^{10}\right]-\gamma \frac{1}{2} \lambda^{\mathrm{T}}\left[X^{i}, \lambda\right]\right)^{2} \\
& \left.+i \lambda^{\mathrm{T}} \gamma_{i}\left[X^{i}, \lambda\right]\right)+\frac{1}{2} \beta \mathcal{T} \operatorname{Tr}(1) . \tag{16}
\end{align*}
$$

Here $\alpha, \beta$ and $\gamma$ appear due to dimensional considerations in going from the bracket to the commutator and also from integration to trace. We will fix $\alpha$ and $\beta$ later.

The action (16) has a gauge symmetry which may be identified with area-preserving symmetry of the supermembrane [13]. It is defined by an arbitrary matrix $\Lambda$ :

$$
\begin{align*}
\delta_{\text {gauge }} X^{i} & =i\left[X^{i}, \Lambda\right] \\
\delta_{\text {gauge }} \lambda & =i[\lambda, \Lambda], \\
\delta_{\text {gauge }} X^{10} & =i\left[X^{10}, \Lambda\right] . \tag{17}
\end{align*}
$$

[^2]Furthermore, the action (16) is invariant under SUSY transformations

$$
\begin{align*}
\delta X^{i} & =0 \\
\delta X^{10} & =\frac{1}{2} \eta^{\mathrm{T}} \lambda, \\
\delta \lambda & =\eta, \tag{18}
\end{align*}
$$

where $\eta$ is an anti-commuting $S O(9)$ spinor, and it can be shown that the above transformations form space-time SUSY algebra

$$
\begin{align*}
{\left[\delta_{\eta}, \delta_{\eta^{\prime}}\right] X^{i} } & =0, \\
{\left[\delta_{\eta}, \delta_{\eta^{\prime}}\right] X^{10} } & =\eta^{\prime \mathrm{T}} \eta, \\
{\left[\delta_{\eta}, \delta_{\eta^{\prime}}\right] \lambda } & =0, \tag{19}
\end{align*}
$$

which for $X^{10}$ can be understood as a non-zero translation, because of $\left\{q_{A}, q_{B}\right\}=\Gamma^{10} P_{10} \delta_{A B}$. Here, the 10th direction is appearing as the 11th direction in the superGalilean algebra $[1,15]^{3}$.

## 3 Solutions with vanishing quantum corrections

In this section we describe certain configurations that are the solutions of the classical equations of motion, and show that the quantum corrections at one-loop order vanish for these configurations. So these solutions, as is expected from similar ones in M-theory, show Bogomol'nyi-Prasad Sommerfield (BPS) behaviour.

The one-loop effective action around the classical solutions

$$
X^{10}=\lambda=0,
$$

is computed in Appendix B, and the result is

$$
\begin{align*}
W & =\frac{1}{2} \operatorname{Tr} \log \left(P_{k}^{2} \delta_{I J}-2 i F_{i j}\right) \\
& -\frac{1}{4} \operatorname{Tr} \log \left(P_{i}^{2}+\frac{i}{2} F_{i j} \gamma^{i j}\right)-\operatorname{Trlog}\left(P_{i}^{2}\right) \tag{20}
\end{align*}
$$

assuming the definitions

$$
\begin{equation*}
P_{i} *=\left[p_{i}, *\right], \quad F_{i j} *=\left[f_{i j}, *\right], \quad f_{i j}=i\left[p_{i}, p_{j}\right], \tag{21}
\end{equation*}
$$

${ }^{3}$ In general, to find the complete SUSY transformations, one
must search for those which respect $\kappa$-symmetry gauge- fixing
by solving the equation
$\Gamma^{+} \theta=0 \leftrightarrow \Gamma^{+}(\theta+\epsilon+(1-\Gamma) \kappa)=0 \Rightarrow \Gamma^{+}(\epsilon+(1-\Gamma) \kappa)=0$.
This is a constraint equation between SUSY and $\kappa$-symmetry parameters $\epsilon$ and $\kappa$, as global and local spinors, respectively. A rapid solution is $\kappa=0$ and $\epsilon \sim\binom{\eta}{\eta}$, which leads to SUSY transformations (18). Another closed-form solution seemed inaccessible in our static case. A similar observation is reported as a result of non-linearities of equations of motion [12]. So we just keep (18).
where $p_{i}$ is classical solution of $X_{i}$.
Every solution with

$$
\begin{equation*}
F_{i j}=0, \quad \forall i, j, \tag{22}
\end{equation*}
$$

leads to vanishing of the one-loop effective action, due to the following algebra:

$$
W \sim\left(\frac{10}{2}-\frac{16}{4}-1\right) \operatorname{Tr} \log \left(P_{i}^{2}\right)=0
$$

We next search for these solutions ${ }^{4}$.
To begin, we consider a solution of (12) which represents a single flat static membrane. With the conditions $X^{10}=\lambda=0$, the equations of motion (12) are

$$
\left\{X^{i},\left\{X^{i}, X^{j}\right\}\right\}=0
$$

Then

$$
\begin{equation*}
X^{1}=\sigma_{1}, X^{2}=\sigma_{2}, \text { other } X^{i}=0 \tag{23}
\end{equation*}
$$

represent a single membrane solution,

$$
\left\{X^{1}, X^{2}\right\}=\left\{\sigma_{1}, \sigma_{2}\right\}=e=1
$$

due to the equation of motion of $e$. In the matrix version the conditions $X^{10}=\lambda=0$ give

$$
\left[X^{i},\left[X^{i}, X^{j}\right]\right]=0
$$

which, analogous to (23), leads to

$$
\begin{equation*}
X^{1}=\frac{L_{1}}{\sqrt{2 \pi n}} q, \quad X^{2}=\frac{L_{2}}{\sqrt{2 \pi n}} p, \quad \text { other } X^{i}=0 \tag{24}
\end{equation*}
$$

with $[q, p]=i$ and $0 \leq q, p \leq \sqrt{2 \pi n}$ eigenvalue distributions. This solution represents a 2 -dimensional object extended in $X^{1}$ and $X^{2}$ directions, and clearly it satisfies (22), thus is stable under quantum fluctuations. Also, because of the spectrum of $p$ and $q$, the area of the 2dimensional object (M2-brane) is $L_{1} L_{2}$.
${ }^{4}$ The point-like configurations which may be represented by
the solutions

$$
X^{i}=\operatorname{diag}\left(x_{1}^{i}, x_{2}^{i}, \ldots, x_{n}^{i}\right), \quad X^{10}=\lambda=0
$$

are not acceptable because of vanishing $\bar{g}$ in (9). This is consistent with the fact that the individual 11-dimensional supergravitons, which are candidates for "quark" substructure of our model (due to their role in the infinite- momentum-frame M (atrix) model as "partons") cannot be studied as static configurations in 11 dimensions, because they are massless. This argument will also be supported by the equation of motion of $n$, the size of the matrices. By inserting the solutions introduced above into the action, one finds

$$
S=0+\frac{1}{2} \beta \mathcal{T} n
$$

The equation of motion for $n$ has no solution (it results in $1=0$ ).

There are also solutions corresponding to two parallel M2-branes,

$$
\begin{aligned}
& X^{1}=\left(\begin{array}{cc}
\frac{L_{1}}{\sqrt{2 \pi n}} q & 0 \\
0 & \frac{L_{1}}{\sqrt{2 \pi n}} q
\end{array}\right) \equiv p^{1}, \\
& X^{2}=\left(\begin{array}{cc}
\frac{L_{2}}{\sqrt{2 \pi n}} p & 0 \\
0 & \frac{L_{2}}{\sqrt{2 \pi n}} p
\end{array}\right) \equiv p^{2}, \\
& X^{3}=\left(\begin{array}{cc}
r / 2 & 0 \\
0 & -r / 2
\end{array}\right) \equiv p^{3},
\end{aligned}
$$

$$
\begin{equation*}
\text { other } \quad X^{i}=\lambda=0, \tag{25}
\end{equation*}
$$

extending in $X^{1}$ and $X^{2}$ directions and at the distance $r$ in the $X^{3}$ direction. Again, this solution clearly satisfies (22), which means that the two M2-branes are under the no-force condition.

## 4 M2-brane and anti-M2-brane long-range interaction

In this section we calculate the long-range interaction between an M2-brane and anti-M2-brane in parallel. Solutions corresponding to two membranes with opposite charges were introduced in [16]:

$$
\begin{aligned}
& X^{1}=\left(\begin{array}{cc}
\frac{L_{1}}{\sqrt{2 \pi n}} q & 0 \\
0 & \frac{L_{1}}{\sqrt{2 \pi n}} q
\end{array}\right) \equiv p^{1}, \\
& X^{2}=\left(\begin{array}{cc}
\frac{L_{2}}{\sqrt{2 \pi n}} p & 0 \\
0 & -\frac{L_{2}}{\sqrt{2 \pi n}} p
\end{array}\right) \equiv p^{2}, \\
& X^{3}=\left(\begin{array}{cc}
r / 2 & 0 \\
0 & -r / 2
\end{array}\right) \equiv p^{3},
\end{aligned}
$$

$$
\begin{equation*}
\text { other } \quad X^{i}=\lambda=0, \tag{26}
\end{equation*}
$$

where $[q, p]=i$. To calculate the potential between these membranes, one must find the one-loop effective action of (16). The one-loop effective action $W$ was introduced in the previous section (and calculated in Appendix 2),

$$
\begin{align*}
W & =\frac{1}{2} \operatorname{Tr} \log \left(P_{i}^{2} \delta_{I J}-2 i F_{i j}\right) \\
& -\frac{1}{4} \operatorname{Tr} \log \left(P_{i}^{2}+\frac{i}{2} F_{i j} \gamma^{i j}\right)-\operatorname{Trlog}\left(P_{i}^{2}\right), \tag{27}
\end{align*}
$$

where $P_{i} *=\left[p_{i}, *\right], F_{i j} *=\left[f_{i j}, *\right], f_{i j}=i\left[p_{i}, p_{j}\right]$.
The calculations of (27) with solutions like (26) are similar to those of [14] for the interaction between two anti-parallel D-strings. For solutions (26) we have $\left[p_{i}, f_{i j}\right]$ $=c-$ number, which means that $P_{i}^{2}$ and $F_{i j}$ are simultaneously diagonalizable. Also $\left[P_{1}, P_{2}\right] \sim i$, which means that $P_{i}^{2}$ behaves like a harmonic oscillator. The steps of calculations are presented in [14], and the result is

$$
\begin{equation*}
W=(-8 n)\left(\frac{L_{1} L_{2}}{2 \pi n}\right)^{3} \frac{1}{r^{6}}+O\left(\frac{1}{r^{8}}\right), \tag{28}
\end{equation*}
$$

which is in agreement with the 11-dimensional supergravity results for the interaction of an M2-brane and anti-M2brane $[16,17]$. It is notable that this result is in the uncompactified limit of 11-dimensional supergravity, in contrast to the result of light-cone M (atrix) theory ( $W(r) \sim 1 / r^{5}$ ) [16].

The result (28) can be used for fixing the parameters $\alpha$ and $\beta$ in (16). By inserting (24) in (16), one finds

$$
\begin{equation*}
S=\left(\frac{1}{4}\right) \alpha \mathcal{T}\left(\frac{L_{1} L_{2}}{2 \pi n}\right)^{2} n+\frac{\beta \mathcal{T}}{2} n \tag{29}
\end{equation*}
$$

and the equation of motion of $n$ gives

$$
\begin{equation*}
\frac{L_{1} L_{2}}{2 \pi n}=\sqrt{\frac{2 \beta}{\alpha}} \tag{30}
\end{equation*}
$$

resulting in

$$
\begin{equation*}
S=\frac{1}{2 \pi} \sqrt{\frac{\alpha \beta}{2}}\left(\mathcal{T} L_{1} L_{2}\right)=T_{M}\left(\mathcal{T} L_{1} L_{2}\right) \tag{31}
\end{equation*}
$$

in which the second equality is the action of a flat membrane with $T_{M}$ as its tension. (31) gives

$$
\begin{equation*}
T_{M}=\frac{1}{2 \pi} \sqrt{\frac{\alpha \beta}{2}} . \tag{32}
\end{equation*}
$$

By comparing (28) with 11-dimensional supergravity interaction [16], one finds

$$
\begin{equation*}
\frac{L_{1} L_{2}}{2 \pi n}=\sqrt{\frac{24 \pi \mathcal{T}}{T_{M}}} . \tag{33}
\end{equation*}
$$

By using $(30,32,33)$ and extracting an irrelevant numerical factor, $\alpha$ and $\beta$ are fixed as follows:

$$
\begin{equation*}
\alpha=\sqrt{\frac{T_{M}^{3}}{\mathcal{T}}}, \quad \beta=12 \pi \sqrt{T_{M} \mathcal{T}} \tag{34}
\end{equation*}
$$

By choosing $\mathcal{T}=T_{M}^{-1 / 3}$, the action (16) becomes:

$$
\begin{align*}
S & =-\frac{1}{2} T_{M}^{4 / 3} \operatorname{Tr}\left(\frac{1}{2}\left[X^{i}, X^{j}\right]^{2}\right. \\
& +\left(\left[X^{i}, X^{10}\right]-\gamma \frac{1}{2} \lambda^{\mathrm{T}}\left[X^{i}, \lambda\right]\right)^{2} \\
& \left.+i \lambda^{\mathrm{T}} \gamma_{i}\left[X^{i}, \lambda\right]\right)+6 \pi \operatorname{Tr}(1) \tag{35}
\end{align*}
$$

## 5 Conclusion and discussions

In this paper we have introduced a matrix model of the static configurations of M-theory. By construction, the large $n$-limit of the model is, at least classically, equivalent with static supermembrane action after $\kappa$-symmetry gauge fixing. We calculated the long-range interaction of a M2-brane and an anti-M2-brane solution in this model and found it to be in agreement with the 11-dimensional supergravity results.

By definition M-theory reduces to various string theories and their compactifications. However, a model for static configurations of M-theory can not be interpreted exactly as a string theory, because there are static configurations in string theories which are not static in uncompactified M-theory (e.g., non-moving D0-branes in IIA theory, which are known to be Kaluza-Klein modes of massless supergravitons of 11-dimensional supergravity, and so they move with the speed of light in 11 dimensions). Notice that the reverse of the above argument is not valid; static configurations in M-theory remain static after compactification. So compactifications of the static matrix model are especially interesting.

## Appendix 1 Conventions and notations

Signatures: $g_{a b}=(-,+,+)$,
$\eta_{\mu \nu}=(-,+,+,+,+,+,+,+,+,+,+)$,
$\epsilon^{0 r s}=-\epsilon^{r s}, \quad \bar{\theta}=\theta^{\dagger} \Gamma_{0},\left[\Gamma^{\mu}, \Gamma^{\nu}\right]_{+}=2 \eta^{\mu \nu}$,
$\Gamma^{\mu \dagger}=\Gamma^{0} \Gamma^{\mu} \Gamma^{0}, \Gamma^{\mu \nu}=1 / 2\left(\Gamma^{\mu} \Gamma^{\nu}-\Gamma^{\nu} \Gamma^{\mu}\right)$,
$\Gamma^{0}=\left(\begin{array}{cc}0 & -1_{16} \\ 1_{16} & 0\end{array}\right), \quad \Gamma^{10}=\left(\begin{array}{cc}1_{16} & 0 \\ 0 & -1_{16}\end{array}\right)$,
$\Gamma^{i}=\left(\begin{array}{cc}0 & \gamma_{16}^{i} \\ \gamma_{16}^{i} & 0\end{array}\right), \Gamma^{+}=\Gamma^{0}+\Gamma^{10}$,
$\gamma_{16}^{i}{ }^{\dagger}=\gamma_{16}^{i}{ }^{*}=\gamma_{16}^{i},\left[\gamma^{i}, \gamma^{j}\right]_{+}=2 \delta^{i j}$,
$\Gamma^{1} \Gamma^{2} \ldots \Gamma^{9} \Gamma^{10}=\Gamma^{0}$.

## Appendix 2 One-loop effective action

The calculation of this part is similar to that in [14]. In this part we decompose the matrices $X$ and $\theta$ to classical solutions and quantum fluctuations as follows:

$$
\begin{align*}
X^{i} & =\left(p^{i}\right)_{\text {class. }}+a^{i}, \\
\lambda & =(0)_{\text {class. }}+\phi, \\
X^{10} & =(0)_{\text {class. }}+a^{10}, \tag{36}
\end{align*}
$$

where $(\ldots)_{\text {class. }}$ are classical solutions and the remaining right-hand side are quantum fluctuations around classical solutions. After expanding the action (16) up to quadratic terms in fluctuations, and using equations of motion, one finds

$$
\begin{align*}
\Delta S & =-\operatorname{Tr}\left(\frac{1}{2}\left[p_{i}, a_{J}\right]^{2}+\left[p_{i}, p_{j}\right]\left[a_{i}, a_{j}\right]-\frac{1}{2}\left[p_{i}, a_{i}\right]^{2}\right. \\
& \left.+\frac{i}{2} \phi^{\mathrm{T}} \gamma^{i}\left[p_{i}, \phi\right]\right) . \tag{37}
\end{align*}
$$

We have ghosts, because of the gauge invariance introduced in the text,

$$
S_{\text {ghost }}=-\operatorname{Tr}\left(\frac{1}{2}\left[p_{i}, a_{i}\right]^{2}+\left[p_{i}, b\right]\left[p_{i}, c\right]\right)
$$

By introducing the adjoint operators

$$
\begin{equation*}
P_{i} *=\left[p_{i}, *\right], \quad F_{i j} *=\left[f_{i j}, *\right], \quad f_{i j}=i\left[p_{i}, p_{j}\right], \tag{38}
\end{equation*}
$$

the final form of the action will be
$S_{2}=\operatorname{Tr}\left(\frac{1}{2}\left(a_{I} P_{i}^{2} \delta_{I J} a_{J}-a_{i} 2 i F_{i j} a_{j}\right)-\frac{i}{2} \phi^{\mathrm{T}} \gamma^{i} P_{i} \phi+b P_{i}^{2} c\right)$.
By inserting $S_{2}$ into the path integral, the one-loop effective action is obtained:

$$
\begin{align*}
W & =-\log \int[\mathrm{d} a][\mathrm{d} \phi][\mathrm{d} c][\mathrm{d} b] \mathrm{e}^{-S_{2}} \\
& =\frac{1}{2} \operatorname{Tr} \log \left(P_{i}^{2} \delta_{I J}-2 i F_{i j}\right) \\
& -\frac{1}{4} \operatorname{Tr} \log \left(P_{i}^{2}+\frac{i}{2} F_{i j} \gamma^{i j}\right)-\operatorname{Tr} \log \left(P_{i}^{2}\right) . \tag{39}
\end{align*}
$$

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[^1]:    ${ }^{1}$ In fact, we could do gauge-fixing before restricting the action to its static regime by the ansatz (5).

[^2]:    ${ }^{2}$ There is a factor $n$ for $n \times n$ matrices in going from bracket to commutator and also from integration to trace. Here we absorbed the factor every time in commutator entries.

